

# Fitting Data with Shift Invariant Spaces

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# Good Models for Signal Processing

## Shift Invariant Spaces (SIS)

Def.: A SIS is a closed subspace  $V \subset L^2(\mathbb{R}^d)$  such that for all  $k \in \mathbb{Z}^d$

$$f \in V \text{ if and only if } f(\cdot - k) \in V$$

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$V(\phi_1, \dots, \phi_n)$  will denote the  $L^2$ -closure of

$$\text{Span}\{\phi_i(x - k) : k \in \mathbb{Z}, i = 1, \dots, n\}$$

These SISs are called **finitely generated**.

## Advantages of using SIS

- Suitable for sampling
- Easy to handle through its generators
- Provide good algorithms for processing
- Include wavelet subspaces

# Examples

- Spline Spaces
- Finite Elements
- Spaces of Band Limited Functions
- Wavelet subspaces

Usually in signal processing applications the signals are assumed to be band-limited. That means that the signals belong to one of the Paley-Wiener spaces

$$PW_{\Omega} = \{f \in L^2 : \text{supp}(\hat{f}) \subset [-\Omega, \Omega]\}.$$

Frequencies outside of the  $\Omega$  interval are assumed to correspond to noise. This assumption has many theoretical and practical advantages. For example a function  $f \in PW_{\Omega}$  can be recovered from its samples  $f(\frac{k}{2\Omega})$  as

$$f(x) = \sum_k f\left(\frac{k}{2\Omega}\right) s\left(x - \frac{k}{2\Omega}\right) \quad \text{with } s(x) = \frac{\sin(2\pi\Omega x)}{\pi x}.$$

However, in many applications, this assumption is not very realistic.

We will then consider finitely generated SIS

$$V = V(\phi_1, \dots, \phi_n),$$

where the integer translates of  $\phi_1, \dots, \phi_n$  form a frame of  $V$ .  
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Let  $H$  be a separable Hilbert Space.

$\{v_j : j \in J\} \subset H$  is a **frame** of  $H$  if there exist constants  $0 < A \leq B < +\infty$  such that for every  $f \in H$

$$A\|f\|^2 \leq \sum_{j \in J} |\langle f, v_j \rangle|^2 \leq B\|f\|^2$$



If  $\{v_j\}_{j \in J}$  is a frame of  $H$ , then every  $f \in H$  has a representation

$$f = \sum_j \langle f, v_j \rangle \tilde{v}_j$$

where  $\{\tilde{v}_j\}$  is a dual frame. If  $A = B = 1$  the frame is called **tight** and

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Frames produce redundant decompositions that have shown to be good for many signal processing applications, in particular for denoising.

**Theorem:** Every finitely generated SIS  $V$  has a tight frame of translates of a finite number of functions.

That is there exist  $\phi_1, \dots, \phi_r \in V$  such that

$\{\phi_i(x - k) : k \in \mathbb{Z}^d, i = 1, \dots, r\}$  is a tight frame of  $V$ . In particular each  $f \in V$  can be decomposed as

$$f(x) = \sum_{i=1}^r \sum_k c_k^i \phi_i(x - k),$$

with  $\{c_k^i\}_k \in l^2(\mathbb{Z}^d), i = 1, \dots, r$

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Can we determine the space completely from this set of signals?

If yes, in which way?



# Determining Sets

The unknown space model:

$V = V(\Phi)$  a shift invariant space of length  $n$ .

$\{\phi_i(x - k) : i = 1, \dots, n, k \in \mathbb{Z}^d\}$  Riesz Basis of  $V$ .

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Main goal:

Find necessary and sufficient conditions on finite subsets  $\mathcal{F} \subset V(\Phi)$  such that any  $g \in V$  can be recovered from  $\mathcal{F}$ .

$\mathcal{F}$  is a determining set for  $V(\Phi)$  if and only if

$$V(\Phi) = V(f_1, f_2, \dots, f_m).$$

Here  $V(f_1, f_2, \dots, f_m) = \text{closure}_{L_2} \{ \text{span}\{f_i(x - k) : f_i \in \mathcal{F}, k \in \mathbb{Z}\} \}$ .

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**Proposition:** If  $\mathcal{F}$  is a determining set for  $V$  then  $\text{card}(\mathcal{F}) \geq n$ .

## Solution to Problem I

For each subset  $F_\ell \subset \mathcal{F}$  of size  $n$ , we define the set

$$A_\ell = \{\omega : \det G_{F_\ell}(\omega) \neq 0\}, \quad 1 \leq \ell \leq L = \binom{m}{n},$$

where  $G_{F_\ell}$  is the  $n \times n$  Gramian matrix for the vector  $F_\ell$ .  
(i.e..  $G_{F_\ell}(\omega) = \sum_{k \in \mathbb{Z}^d} \hat{F}_\ell(\omega + k) \hat{F}_\ell^*(\omega + k)$ )

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**Theorem 1** A set  $\mathcal{F} = \{f_1, \dots, f_m\} \subset V(\Phi)$  is a determining set for  $V(\Phi)$  if and only if the set

$$Z = \bigcap_{\ell=1}^L A_\ell^c, \quad \text{has Lebesgue measure zero}$$

Moreover, if  $\mathcal{F}$  is a determining set for  $V(\Phi)$ , then the vector function

$$\widehat{\Psi}(\omega) := G_{F_1}^{-\frac{1}{2}}(\omega)\widehat{F}_1(\omega)\chi_{B_1}(\omega) + \cdots + G_{F_L}^{-\frac{1}{2}}(\omega)\widehat{F}_L(\omega)\chi_{B_L}(\omega) \quad (1)$$

where  $B_1 := A_1, B_\ell := A_\ell - \bigcup_{j=1}^{\ell-1} A_j, \ell = 2, \dots, L,$

generates an orthonormal basis  $\{\psi_i(x - k) : i = 1, \dots, n, k \in \mathbb{Z}^d\}$  of  $V(\Phi)$ .



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- the class of functions from which the data is drawn may not be a shift-invariant space.
- the shift-invariant space hypothesis is correct but the assumptions about the number of generators is wrong.
- the a priori hypothesis is correct but the data is corrupted by noise.

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let  $\mathcal{V} = \{V \subset L^2(\mathbb{R}^d) : V = V(\Phi), \Phi \text{ a frame of length } n\}$

we want to find a space  $V \in \mathcal{V}$  such that

$$\sum_{i=1}^m \|f_i - P_V f_i\|^2 \leq \sum_{i=1}^m \|f_i - P_W f_i\|^2$$

for all  $W \in \mathcal{V}$ .



That is, given  $\mathcal{F}$ , find a space  $V \in \mathcal{V}$  such that  $V$  minimizes the least square error

$$E(\mathcal{F}, n) = \sum_{i=1}^m \|f_i - P_V f_i\|^2,$$

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- Does such space exist?
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- Can we construct the generators of the space?

## Results

**Theorem 2** Let  $F = (f_1, \dots, f_m)^T$  be a vector of functions with components in  $L^2(\mathbb{R}^d)$ , and  $n \leq m$  be given.

1. There exists  $V \in \mathcal{V}_n$  such that

$$\sum_{i=1}^m \|f_i - P_V f_i\|^2 \leq \sum_{i=1}^m \|f_i - P_W f_i\|^2, \quad \forall W \in \mathcal{V}_n \quad (2)$$

2. The optimal shift-invariant space  $V$  in (2) can be chosen such that  $V \subset \mathcal{V}(F)$ .

**Theorem 3** *Under the same assumptions as in the previous theorem, let  $\lambda_1(\omega) \geq \lambda_2(\omega) \geq \dots \geq \lambda_m(\omega)$  be the eigenvalues of  $G_F(\omega)$ , then*

1. *The eigenvalues  $\lambda_i(\omega)$ ,  $1 \leq i \leq m$  are measurable functions in  $L^2([0, 1]^d)$  and*

$$\sum_{i=1}^m \|f_i - P_V f_i\|^2 = \sum_{i=n+1}^m \int_{[0,1]^d} \lambda_i(\omega) d\omega \quad (3)$$

2. Let  $E_i := \{\omega : \lambda_i(\omega) \neq 0\}$ .

Define  $\tilde{\sigma}_i(\omega) = \lambda_i^{-1/2}(\omega)$  on  $E_i$  and  $\tilde{\sigma}_i(\omega) = 0$  on  $E_i^c$ .

Then, there exists a choice of eigenvectors  $v_1(\omega), \dots, v_n(\omega)$  associated with the first  $n$  largest eigenvalues such that the functions defined by

$$\hat{\phi}_i(\omega) = \tilde{\sigma}_i(\omega) \sum_{j=1}^m v_{ij}(\omega) \hat{f}_j(\omega), \quad i = 1, \dots, n, \omega \in \mathbb{R}^d$$

are measurable functions in  $L^2(\mathbb{R}^d)$ .

Furhermore, the corresponding vector function  $\Phi = (\phi_1, \dots, \phi_n)$  is a generator for  $V$  and the set  $\{\phi_i(x - k), k \in \mathbb{Z}^d, i = 1, \dots, n\}$  is a tight frame for  $V$ .