The frame complex of a vector space with a Hermitian form

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Definition

Under these conditions, we say that (V, Ψ) is a unitary space of dimension *n* over *K*.



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Finite fields

If $K = \mathbb{F}_r$, then $r = q^2$ is a square and $\sigma(x) = x^q$. Moreover, (V, Ψ) is uniquely determined:

$$\Psi(v,w)=\sum_{i=1}^n v_i w_i^q.$$



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What is known about $\mathcal{S}(V)$?

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Not too much.

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Not too much. Indeed, $\mathcal{S}(V) \cup \{0, V\}$ is not even a lattice in general!

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 G(V) graph with vertices the non-degenerate 1-dimensional subspaces of V, and with edges corresponding to the orthogonality relation: (S, T) ∈ G(V) iff S ⊥ T;

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- D(V) = poset of non-trivial orthogonal decompositions of V.
 Order given by refinement: π ≤ π' if π is finer than π'.

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③ Then the face-poset of $\mathcal{F}(V)$ is homotopy equivalent to

$$\hat{\mathcal{F}}(V) = \{ \text{ frames of size } \neq n-1 \},$$

with dim $\hat{\mathcal{F}}(V) = n - 2$.

Suppose that dim $V = n \ge 2$.

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- **③** If *n* ≥ 5 and $(n, K) \neq (6, \mathbb{F}_{2^2})$, then $\mathcal{F}(V)$ is simply connected.

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- 3 If $n \ge 5$ and $(n, K) \ne (6, \mathbb{F}_{2^2})$, then $\mathcal{F}(V)$ is simply connected.
- If $(n, K) = (6, \mathbb{F}_{2^2})$ then $\pi_1(\mathcal{F}(V)) = C_2 \times C_2$.



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Question

If $|K| \ge 4^2$, n = 4, is $\mathcal{F}(V)$ simply connected?

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- $L(G) = \operatorname{Id} D^{-1}A$ is the normalised Laplacian.

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③ Moreover, $\mathcal{G}(V)$ is regular of degree

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Theorem

If $q \neq 2$ and $n \geq 3$, the eigenvalues of $\mathcal{G}(V)$ are:

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In particular, the smallest non-zero eigenvalue of $L(\mathcal{G}(V))$ is $1 - d_n^{-1}q^{n-2}$.

Higher connectivity for $H_*(\mathcal{F}(V), \mathbb{Q})$.

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- **2** If $n \ge 7$, $\widetilde{H}_i(\mathcal{F}(V), \mathbb{Q}) = 0$ for all $i \le \frac{n}{2}$.
- 3 In fact, if $q \ge 11$ and $n \ge 8$, then $\widetilde{H}_i(\mathcal{F}(V), \mathbb{Q}) = 0$ for all $i \le \frac{3}{4}n 1$.

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Corollary

Similar results are transferred to $\mathcal{S}(V)$ and $\mathcal{D}(V)$ via the poset map

$$\mathcal{F}(V)^{n-2} \longrightarrow \mathcal{S}(V), \quad \{V_1, V_2, \dots, V_r\} \mapsto V_1 \oplus V_2 \oplus \dots \oplus V_r,$$

and the wedge relation between $\mathcal{S}(V)$ and $\mathcal{D}(V)$.

¡Muchas gracias!