Geometric regularity estimates for quasilinear evolution models

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Introduction

In this Lecture we are interested in studying quantitative features for evolution models of $p-{\rm Laplacian}$ type as follows

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$$\mathcal{Q}u := \frac{\partial u}{\partial t} - \operatorname{div}(|\nabla u|^{p-2} \nabla u) = f(x, t) \quad \text{in} \quad \Omega_T, \quad p > 2$$
(1.1)

where

 $\checkmark \quad \Omega_T := \Omega \times (0,T)$ with $\Omega \subset \mathbb{R}^N$ a bounded and regular domain;

✓ $f \in L^{q,r}(\Omega_T)$ (a Lebesgue space with mixed norms) endowed with the norm

$$\|f\|_{L^{q,r}(\Omega_T)} := \left(\int_0^T \left(\int_\Omega |f(x,t)|^q dx\right)^{\frac{r}{q}} dt\right)^{\frac{1}{r}} \bullet.$$

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Motivation

A fundamental issue in linear and nonlinear PDEs consists in inferring which is the expected regularity to weak solutions.

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$$\mathcal{H}u := \frac{\partial u}{\partial t}(x,t) - \Delta u(x,t) = f \text{ in } Q_1^- := B_1 \times (-1,0].$$
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A priori estimate to Hom. problem Integrability of the Vs with "frozen" coef. source term

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A priori estimate to Hom. problem Integrability of the Vs with "frozen" coef. source term

Indeed, $v(x,t) := \frac{u(\rho x, \rho^2 t)}{\rho^{\kappa}}$, $\kappa \in (0, 2]$ verifies in the weak sense:

$$\frac{\partial v}{\partial t}(x,t) - \Delta v(x,t) = \rho^{2-\kappa} f(\rho x,\rho^2 t) := f_\rho(x,t) \quad \Rightarrow \quad \|f_\rho\|_{L^{q,r}(\mathbb{Q}^-_1)} \leq \rho^{2-\kappa-\left(\frac{n}{q}+\frac{2}{r}\right)} \|f\|_{L^{q,r}(\mathbb{Q}^-_1)}.$$

Sharp regularity estimates

More integrability of $f \Rightarrow$ More (local) regularity of u

Theorem (da S. and Teixeira, Math. Ann. 18)

Let u be a bounded weak solution to (1.2) then

$f\in L^{q,r}(Q_1^-)$	Sharp Regularity
$1 < \frac{n}{q} + \frac{2}{r} < 2$	$C_{loc}^{\varsigma,\frac{\varsigma}{2}}(Q_1^-)$
$\frac{n}{q} + \frac{2}{r} = 1$	$C_{loc}^{0,Log-Lip}(Q_1^-)$
$0 < \frac{n}{q} + \frac{2}{r} < 1$	$C^{1+\zeta,\frac{1+\zeta}{2}}_{loc}(Q_1^-)$
$BMO \supset L^{\infty,\infty} \simeq L^{\infty}$	$C_{loc}^{1,Log-Lip}(Q_1^-)$

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Introduction

Our result and its natural obstacles References

Explicit representation of the moduli of continuity

Theorem (da S. and Teixeira, Math. Ann. 18)

Let u be a bounded weak solution to (1.2) then

$\mathbf{f}\in L^{q,r}(\mathbf{Q}_1^-)$	Sharp Regularity
$1 < \frac{n}{q} + \frac{2}{r} < 2$	$C_{loc}^{\varsigma,\frac{\varsigma}{2}}(Q_1^-)$
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$$\boldsymbol{\varsigma} := 2 - \left(\frac{n}{q} + \frac{2}{r}\right)$$
 and $\boldsymbol{\zeta} := \min\left\{\alpha_{\operatorname{Hom}}^{-}, 1 - \left(\frac{n}{q} + \frac{2}{r}\right)\right\}$

Sharp Lipschitz Logarithmical moduli of continuity

Theorem (da S. and Teixeira, Math. Ann. 18)

Let u be a bounded weak solution to (1.2) then

$f\in L^{q,r}(Q_1^-)$	Sharp Regularity
$1 < \frac{n}{q} + \frac{2}{r} < 2$	$C_{loc}^{\varsigma,\frac{\varsigma}{2}}(Q_1^-)$
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$BMO \supset L^{\infty,\infty} \simeq L^{\infty}$	$C_{loc}^{1,Log-Lip}(Q_1^-)$

$$\tau(s) := s \log s^{-1}$$
 and $\psi(r) := s^2 \log s^{-1}$

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Motivation

One Million Dollar Question:

What should we expect from Nonlinear Scenery $(p \neq 2)$?

Recently, under the condition $:\frac{1}{r} + \frac{n}{pq} < 1 < \frac{2}{r} + \frac{n}{q}$ for p > 2 and by combining geometric tangential methods and intrinsic scaling techniques (cf. [5]), the sharp (geometric) $C_{loc}^{\alpha,\frac{\alpha}{\theta}}$ regularity estimate was established in Teixeira-Urbano^a, where

$$\alpha = \frac{p\left[1 - \left(\frac{1}{r} + \frac{n}{pq}\right)\right]}{p\left[1 - \left(\frac{1}{r} + \frac{n}{pq}\right)\right] + \left(\frac{2}{r} + \frac{n}{q}\right) - 1} \quad \text{and} \quad \theta := 2\alpha + (1 - \alpha)p.$$

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E.V. Teixeira & J.M. Urbano, *A geometric tangential approach to sharp regularity for degenerate evolution equations.* **Anal. PDE** 7 (2014), no. 3, 733-744.

Motivation

One Million Dollar Question:

What should we expect from Nonlinear Scenery $(p \neq 2)$?

Essentially, Teixeira and Urbano leave as open issues the following scenarios:

$\mathbf{f}\in \mathbf{L}^{\mathbf{q},\mathbf{r}}(\mathbf{Q}_1^-)$	Sharp Regularity
$rac{1}{r}+rac{n}{pq}<1$ and $1<rac{2}{r}+rac{n}{q}$	$C_{loc}^{\alpha, \frac{\alpha}{\theta}}$
$rac{1}{r}+rac{n}{pq}<1$ and $1=rac{2}{r}+rac{n}{q}$	Open Problem
$0 < rac{1}{r} + rac{n}{pq} < 1$ and $0 < rac{2}{r} + rac{n}{q} < 1$	Open Problem
$BMO \supset L^{\infty,\infty} \simeq L^{\infty}$	Open Problem



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Motivation

One Million Dollar Question:

What should we expect from Nonlinear Scenery $(p \neq 2)$?

We will provide an affirmative answer in the two last sceneries:

$\mathbf{f}\in \mathrm{L}^{\mathbf{q},\mathbf{r}}(\mathbf{Q}_{1}^{-})$	Sharp Regularity
$rac{1}{r}+rac{n}{pq}<1$ and $1<rac{2}{r}+rac{n}{q}$	$C_{loc}^{lpha,rac{H}{H}}$
(CC) $0 < \frac{1}{r} + \frac{n}{pq} < 1$ and $0 < \frac{2}{r} + \frac{n}{q} < 1$	$C_{loc}^{1+min\left\{\frac{1-\left(\frac{n}{q}+\frac{2}{r}\right)}{p\left[1-\left(\frac{n}{pq}+\frac{1}{r}\right)\right]-\left[1-\left(\frac{n}{q}+\frac{2}{r}\right)\right]}, \alpha_{Hom}^{-}\right\}}$
$BMO\supset L^{\infty,\infty}\simeq L^\infty$	$C_{\text{loc}}^{1+\min\left\{\frac{1}{p-1}, \alpha_{\text{Hom}}^{-}\right\}}$

Another question:

Are there significant changes between the Teixeira-Urbano's case and the other ones?^a

^aCambia, Todo cambia...Mercedes Sosa. Todo cambia, Live in Europe, 1989.

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Motivation

Our Impetus

Therefore, we will focus our attention in establishing sharp (geometric) $C^{1+\alpha}$ regularity estimates for weak solution to (1.1) inside certain critical sets, by using a systematic and modern approach (cf. [1], [2], [3] and [5]).

Motivation

Our Impetus

Therefore, we will focus our attention in establishing sharp (geometric) $C^{1+\alpha}$ regularity estimates for weak solution to (1.1) inside certain critical sets, by using a systematic and modern approach (cf. [1], [2], [3] and [5]).

It is worth highlight that such an estimates play a fundamental role in proving^a:

- Blow-up results and Liouville type results;
- Weak geometric properties (in certain free boundary problems);
- Hausdorff measure estimates (in certain free boundary problems);

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J.V. da Silva & P. Ochoa, *Fully nonlinear parabolic dead core problems*. To appear in **Pacific J. Math.** 2018.

J.V. da Silva, P. Ochoa & A. Silva, *Regularity for degenerate evolution equations with strong absorption.* J. Differential Equations 264 (2018), no. 12, 7270-7293.

Main Theorem

Theorem (Amaral, da S., Ricarte & Teymurazyan, Israel J. Math. 18)

Let $K \subset \subset Q_1^-$, u be a bounded weak solution of (1.1) in Q_1^- and suppose that (CC) are in force. Then u is $C^{1+\alpha}$ (in the parabolic sense), i.e., there exists a (universal) constant M > 0 such that

$$[u]_{C^{1+\alpha}(K)}^* \le M. \left[\|u\|_{L^{\infty}(Q_1^-)} + \|f\|_{L^{q,r}(Q_1^-)} \right],$$

where

$$[u]_{C^{1+\alpha}(K)}^{*} := \sup_{0 < \rho \le \rho_{0}} \left(\inf_{(x_{0},t_{0}) \in \mathcal{C}_{\rho}^{\alpha}(Q_{1}^{-})} \frac{\|u - \mathfrak{l}_{(x_{0},t_{0})}(u)\|_{L^{\infty}(\hat{Q}_{\rho}^{-}(x_{0},t_{0}) \cap K)}}{\rho^{1+\alpha}} \right)$$

and

$$\mathfrak{l}_{(x_0,t_0)}(u)(x) := u(x_0,t_0) + \nabla u(x_0,t_0) \cdot (x-x_0).$$

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Chapter 1: Approximation result

A key step in accessing the tangential path toward the regularity theory available for "frozen" coefficient, homogeneous p-caloric functions is the following result.

Lemma (*p*-caloric Approximation Lemma)

If u is a weak solution of (1.1) in Q_1^- with $\|u\|_{L^{\infty}(Q_1^-)} \leq 1$, then $\forall \varepsilon > 0$ there exists $\delta = \delta(p, n, \varepsilon) > 0$ such that whenever $\|f\|_{L^{q,r}(Q_1^-)} \leq \delta$ there exists a p-caloric function $\phi : Q_{\frac{1}{2}}^- \to \mathbb{R}$ such that

$$\max\left\{\left\|u-\phi\right\|_{L^{\infty}\left(\mathbb{Q}_{\frac{1}{2}}^{-}\right)}, \left\|\nabla(u-\phi)\right\|_{L^{\infty}\left(\mathbb{Q}_{\frac{1}{2}}^{-}\right)}\right\} < \varepsilon.$$

$$(2.1)$$

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Chapter 1: Approximation result

Remark (Normalization and "flatness regime")

Assumptions in the Lemma 3 are not restrictive. Indeed, fixed $\delta > 0$ and s > 0, there exists positive constant $\mu = \mu(\delta, s, \|u\|_{L^{\infty}}, \|f\|_{L^{q,r}})$ such that the function

 $v(x,t) := \mu^s u(\mu^s x, \mu^\tau t),$

fall into in the conditions of Lemma 2.1, where $\tau := 2s(p-1) > 0$,

$$0 < \mu < \min\left\{1, \frac{1}{\sqrt[s]{\|u\|_{L^{\infty}(Q_{1}^{-})}}}, \sqrt[\kappa]{\|f\|_{L^{q,r}(Q_{1}^{-})}}\right\}$$

and

$$\kappa = s\left[(p-1)\left(1-\frac{1}{r}\right) + \frac{1}{r}\right] + sp\left[1-\left(\frac{n}{pq}+\frac{1}{r}\right)\right]$$

Chapter 2: Metric (a priori estimate) Vs Geometry of parabolic cylinder

Lemma (Pseudo first step of induction)

Let u be a weak solution of (1.1) in Q_1^- with $||u||_{L^{\infty}(Q_1^-)} \leq 1$. There exist $\delta > 0$ and $\rho \in \left(0, \frac{1}{2}\right)$ such that if $||f||_{L^{q,r}(Q_1^-)} \leq \delta$, then

$$\sup_{\hat{Q}_{\rho}(x_{0},t_{0})} \left| u(x,t) - \mathfrak{l}_{(x_{0},t_{0})}(u)(x) \right| \leq \rho^{1+\alpha}.$$



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Chapter 2: Metric (a priori estimate) Vs Geometry of parabolic cylinder

Idea of proof.

For $Q_{\rho}^{-}(x_{0},t_{0}) = B_{\rho}(x_{0}) \times (t_{0} - \rho^{\theta},t_{0}]$ with $\theta > 0$ (intrinsic scaling factor):

$$\begin{split} \left\| u - \mathfrak{l}_{(x_0,t_0)}(u) \right\|_{L^{\infty}\left(Q_{\rho}(x_0,t_0)\right)} &\leq \left\| \phi - \mathfrak{l}_{(x_0,t_0)}(\phi) \right\|_{L^{\infty}\left(Q_{\rho}(x_0,t_0)\right)} + |(u - \phi)(x_0,t_0)| \\ &+ \left\| u - \phi \right\|_{L^{\infty}\left(Q_{\rho}(x_0,t_0)\right)} + |\nabla(u - \phi)(x_0,t_0)| \\ &\leq C \sup_{Q_{\rho}(x_0,t_0)} \left(\left| x - x_0 \right| + \sqrt{|t - t_0|} \right)^{1 + \alpha_{\mathrm{Hom}}} + 3\varepsilon \\ &\leq C \rho^{(1 + \alpha_{\mathrm{Hom}})\min\left\{1, \frac{\theta}{2}\right\}} + 3\varepsilon \\ &\leq C \rho^{(1 + \alpha_{\mathrm{Hom}})} + 3\varepsilon \text{ (expected estimate)} \end{split}$$

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Chapter 2: Metric (a priori estimate) Vs Geometry of parabolic cylinder

Idea of proof.

Notice that for p > 2

$$1 < 2 + (2-p)\hat{\alpha} \le \theta(\alpha, p, \rho, \|\nabla u\|) \le 2.$$

In this point, we define the intrinsic correction factor for our (corrected) parabolic cylinders:

$$\sigma := \frac{2}{2 + (2-p)\hat{\alpha}} \in [1,2), \text{ where } \hat{\alpha} := \frac{1 - \left(\frac{n}{q} + \frac{2}{r}\right)}{p\left[1 - \left(\frac{n}{pq} + \frac{1}{r}\right)\right] - \left[1 - \left(\frac{n}{q} + \frac{2}{r}\right)\right]}.$$

Such a definition assures that $\theta \sigma \ge 2$, which allow us put the parabolic cylinder in the correct framework.



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Chapter 2: Metric (a priori estimate) Vs Geometry of parabolic cylinder

Idea of proof.

Coming back to our estimate (now with the corrected cylinder)

$$\hat{Q}^{-}_{\rho^{l}}(x_{0},t_{0}) := B_{\rho^{l}}(x_{0}) \times \left(t_{0} - \rho^{\theta(\sigma+l-1)},t_{0}\right] \subset Q^{-}_{\rho^{l}}(x_{0},t_{0})$$

we can conclude:

$$\begin{aligned} \left\| u - \mathfrak{l}_{(x_0,t_0)}(u) \right\|_{L^{\infty}(\dot{Q}_{\rho}(x_0,t_0))} &\leq C \rho^{(1+\alpha_{\operatorname{Hom}})\min\{1,\frac{\theta\sigma}{2}\}} + 3\varepsilon \\ &\leq C \rho^{(1+\alpha_{\operatorname{Hom}})} + 3\varepsilon \\ &\leq \rho^{1+\alpha} \end{aligned}$$

provided

$$\boldsymbol{\rho} \in \left(0, \min\left\{\frac{1}{2}, \left(\frac{1}{2C}\right)^{\frac{1}{\alpha_{Hom} - \alpha}}\right\}\right) \quad \text{and} \quad \boldsymbol{\varepsilon} \in \left(0, \frac{1}{6}\boldsymbol{\rho}^{1 + \alpha}\right).$$

Chapter 3: The gap in the standard induction process

Different from $C^{1+\zeta}$ regularity estimates proved in the linear setting, we should point out that the former lemma is not enough to proceed with an iterative scheme, because a priori we do not know the equation which would be satisfied by

$$v_k(x,t) := \frac{u(\rho^k x + x_0, \rho^{k\theta} t + t_0) - \mathfrak{l}_k(\rho^k x + x_0)}{\rho^{k(1+\alpha)}},$$

where $\{l_k\}_{k \in \mathbb{N}}$ is sequence of affine functions.



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Chapter 4: Iteration: A new oscillation mechanism

Corollary (First (real) step of induction)

Suppose that the assumptions of previous Lemma are in force. Then,

$$\sup_{\hat{Q}_{\rho}^{-}(x_{0},t_{0})}|u(x,t)-u(x_{0},t_{0})| \leq \rho^{1+\alpha}+\rho|\nabla u(x_{0},t_{0})|$$

In order to obtain a precise control on the influence of magnitude of the gradient of u, we iterate solutions (using the previous Corollary) in corrected ρ -adic cylinders.

Lemma (Iterative process)

Under the assumptions of previous Corollary one has

$$\sup_{\hat{Q}_{\rho^{k}}(x_{0},t_{0})} |u(x,t) - u(x_{0},t_{0})| \le \rho^{k(1+\alpha)} + |\nabla u(x_{0},t_{0})| \sum_{j=0}^{k-1} \rho^{k+j\alpha}.$$
(2.2)

Chapter 4: Iteration: A new oscillation mechanism

Our next result provides the geometric regularity estimate inside critical zone. We define the critical zone as follows:

$$\mathcal{C}^{\alpha}_{\rho}(Q_1^-) := \left\{ (x,t) \in Q_1^-; \left| \nabla u(x,t) \right| \le \rho^{\alpha} \right\}$$

Theorem

Suppose that the assumptions of previous Lemma are in force. Then, there exists a universal constant M>1 such that

$$\sup_{\hat{2}\rho_0^-(x_0,t_0)} |u(x,t) - u(x_0,t_0)| \le M\rho_0^{1+\alpha} \left(1 + |\nabla u(x_0,t_0)|\rho_0^{-\alpha}\right), \ \forall \rho_0 \in (0,\rho).$$

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Proof of Main Theorem

Proof of the Theorem.

WLOG, we may assume that $K = Q_{\frac{1}{2}}^-$ and $(x_0, t_0) = (0, 0)$. Using previous Theorem (re-scaled according to Remark, if needed), we estimate

$$\sup_{\hat{Q}_{\rho_{0}}^{-}} \frac{\left| u(x,t) - \mathfrak{l}_{(0,0)} u(x) \right|}{\rho^{1+\alpha}} \leq \sup_{\substack{\hat{Q}_{\rho_{0}}^{-}}} \frac{\left| u(x,t) - u(0,0) \right|}{\rho_{0}^{1+\alpha}} + \frac{\left| \nabla u(0,0) \right| \rho_{0}}{\rho_{0}^{1+\alpha}} \\ \leq M \left(1 + \left| \nabla u(0,0) \right| \rho_{0}^{-\alpha} \right) + 1 \\ \leq 3M$$



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Final Chapter: The Journey Continues...

Coming back to the open issues:





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Expected regularity estimates





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References





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Thank you very much for your attention : -)!

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